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This volume contains the proceedings of the RAAD 2018 conference, covering major areas of research and development in robotics. It provides an overview on the advances in robotics, more specifically in novel design and applications of robotic systems; dexterous grasping, handling and intelligent manipulation; intelligent cooperating and service robots; advanced robot control; human-robot interfaces; robot vision systems and visual serving

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techniques; mobile robots; humanoid and walking robots; field and agricultural robotics; bio-inspired and swarm robotic systems; developments towards micro and nano-scale robots; aerial, underwater and spatial robots; robot integration in holonic manufacturing; personal robots for ambient assisted living; medical robots and bionic prostheses; intelligent information technologies for cognitive robots etc. The primary audience of the work are researchers as well as engineers in robotics and mechatronics.

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This book highlights recent research on intelligent systems design and applications. It presents 100 selected papers from the 17th International Conference on Intelligent Systems Design and Applications (ISDA 2017), which was held in Delhi, India from December 14 to 16, 2017. The ISDA is a premier conference in the field of Computational Intelligence and brings together researchers, engineers and practitioners whose work involves intelligent systems and their applications in industry and the real world. Including contributions by authors from over 30 countries, the book offers a valuable reference guide for all researchers, students and practitioners in the fields of Computer Science and Engineering.

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Proceedings of the European Control Conference 1995,  
Rome, Italy 5-8 September 1995

This book constitutes the refereed proceedings of the 15th Conference on Advances in Autonomous Robotics, TAROS 2014, held in Birmingham, UK, in September 2014. The 23 revised full papers presented together with 9 extended abstracts were carefully reviewed and selected from 48 submissions. The overall program covers various aspects of robotics, including navigation, planning, sensing and perception, flying and swarm robots, ethics, humanoid robotics, human-robot interaction, and social robotics.

The volume LNAI 12228 constitute the refereed proceedings

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of the 21th Annual Conference "Towards Autonomous Robotics," TAROS 20120, held in Nottingham, UK, in September 2020.\* The 30 full papers and 11 short papers presented were carefully reviewed and selected from 63 submissions. The papers present and discuss significant findings and advances in autonomous robotics research and applications. They are organized in the following topical sections: soft and compliant robots; mobile robots; learning, mapping and planning; human-robot interaction; and robotic systems and applications. \* The conference was held virtually due to the COVID-19 pandemic.

This book focuses on the importance of human factors in the development of safe and reliable unmanned systems. It

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discusses current challenges such as how to improve the perceptual and cognitive abilities of robots, develop suitable synthetic vision systems, cope with degraded reliability in unmanned systems, predict robotic behavior in case of a loss of communication, the vision for future soldier-robot teams, human-agent teaming, real-world implications for human-robot interaction, and approaches to standardize both the display and control of technologies across unmanned systems. Based on the AHFE 2017 International Conference on Human Factors in Robots and Unmanned Systems, held on July 17–21 in Los Angeles, California, USA, this book is expected to foster new discussion and stimulate new advances in the development of more reliable, safer, and highly functional devices for carrying out automated and

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concurrent tasks.

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A comprehensive survey of artificial intelligence algorithms and programming organization for robot systems, combining theoretical rigor and practical applications. This textbook offers a comprehensive survey of artificial intelligence (AI) algorithms and programming organization for robot systems. Readers who master the topics covered will be able to design and evaluate an artificially intelligent robot for applications involving sensing, acting, planning, and learning. A background in AI is not required; the book introduces key AI

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topics from all AI subdisciplines throughout the book and explains how they contribute to autonomous capabilities. This second edition is a major expansion and reorganization of the first edition, reflecting the dramatic advances made in AI over the past fifteen years. An introductory overview provides a framework for thinking about AI for robotics, distinguishing between the fundamentally different design paradigms of automation and autonomy. The book then discusses the reactive functionality of sensing and acting in AI robotics; introduces the deliberative functions most often associated with intelligence and the capability of autonomous initiative; surveys multi-robot systems and (in a new chapter) human-robot interaction; and offers a “metaview” of how to design and evaluate autonomous systems and the ethical

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considerations in doing so. New material covers locomotion, simultaneous localization and mapping, human-robot interaction, machine learning, and ethics. Each chapter includes exercises, and many chapters provide case studies. Endnotes point to additional reading, highlight advanced topics, and offer robot trivia.

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